A LORENTZIAN SIGNATURE MODEL FOR QUANTUM GENERAL RELATIVITY

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ABSTRACT. We give a relativistic spin network model for quantum gravity based on the Lorentz group and its q-deformation, the Quantum Lorentz Algebra. We propose a combinatorial model for the path integral given by an integral over suitable representations of this algebra. This generalises the state sum models for the case of the four-dimensional rotation group previously studied in [1], gr-qc/9709028.

As a technical tool, formulae for the evaluation of relativistic spin networks for the Lorentz group are developed, with some simple examples which show that the evaluation is finite in interesting cases. We conjecture that the '10J' symbol needed in our model has a finite value.

1. Introduction

In [1], we proposed a model for quantized discrete general relativity with a Euclidean signature. The model was constructed by combining the structure of a certain tensor category and of a full subcategory of it with the combinatorics of a triangulated 4-manifold. The category was the representations of U_q so(4), for q a 4n-th root of unity and the subcategory the representations which are called balanced or simple.

The main technical tool was the introduction of spin networks for these representations, which we called relativistic spin networks. The adjective relativistic is used because the relativistic spin networks are related to four-dimensional geometry whereas the original SU(2) spin networks of Penrose [5] are related to three-dimensional geometry. The name anticipated the development of relativistic spin networks for the physically realistic case of the Lorentz group, SO(3,1). The wider context for the model is explained in [2, 3]. It is closely related to topologically invariant models [27, 11, 12, 13, 14].

The purpose of this paper is to supply the analogous concepts to our previous work for the Lorentz group and its q-deformation, $U_qSL(2,\mathbb{C})$. The geometrical description of the relativistic spin network evaluation for SO(3,1) is developed, in which hyperboloids in Minkowski space replace the role played by the sphere S^3 for the SO(4) case [1, 15, 29].

We develop a correspondence between relativistic spin networks and the Lorentzian geometry of simplicies. One of the predictions we make is that the area of a timelike surface is quantized but the area of a spacelike surface can take any value in a continuous range.

After removing a trivial infinite factor of the volume of the hyperbolic space, we obtain a expression for the evaluation of the relativistic spin network associated to a 4-simplex as a multiple integral on hyperbolic space. We conjecture that this integral is absolutely convergent.

The study of the q-deformation of the Lorentzian case is not so far advanced, but we give some observations on this and the possible implications for Lorentzian signature state sum models.

Before explaining our results, we give a brief review of the Euclidean case.

1.1. **Review of the Euclidean model.** The steps of the construction of the model in [1] were as follows:

- 1. Describe the geometry of a discrete Riemannian triangulated 4-manifold by assigning bivectors to the 2-simplices satisfying appropriate constraints.
- 2. Identify the bivectors with Lie algebra elements.
- 3. Quantize the bivectors by replacing the Lie algebra with a sum over its representation category.
- 4. Implement the constraints that the bivectors are simple bivectors by passage to a subcategory.
- 5. Switch to the representations of a quantum group with q a root of unity in order to create a finite model.
- 6. Determine a quantum state for each tetrahedron. This is a morphism intertwining the four representations which are associated to the four boundary faces of the tetrahedron.
- 7. Connect the representations and morphisms around the boundary of each 4-simplex into a closed diagram called a relativistic spin network. The diagram consists of one tetravalent vertex at the centre of each tetrahedon with edges corresponding the four faces of the tetrahedron. Edges corresponding to the common face of two adjacent tetrahedra are then joined. This gives a closed graph embedded in the boundary of the 4-simplex, S^3 . The evaluation of this relativistic spin network determines the amplitude for a single 4-simplex.
- 8. Multiply the amplitudes for each 4-simplex in the space-time manifold together, and then sum over the representation labels introduced to give a discrete version of a path integral.

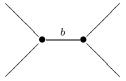
We introduced two variants of the model, given by different relativistic spin networks for the 4-simplex. One of them is based on a 15J-symbol from representation theory (a complex number which is a function of 15 irreducible representations). The other is based on a

new function of 10 irreducible representations which one might call the 10J-symbol¹.

Firstly we describe the model based on the 10J–symbol. There is a uniquely determined morphism which satisfies all the constraints for the tetrahedron, which is taken to be a 4-valent vertex for the relativistic spin network. The vertex was introduced in [1] and generalised to other valencies in [9]. For the q=1 case, the vertex was proved to be the unique one satisfying the constraints for the geometry of a tetrahedron in [6], and its detailed properties were investigated in [4, 7]. This vertex can be regarded as the quantum state determined by quantizing the four bivectors determined by the four faces of a classical geometrical tetrahedron.

Starting with this 4-valent vertex one obtains an amplitude for the 4-simplex which depends on the 10 representation labels at the 10 triangles. The irreducible representations in question are indexed by the integers, and the geometrical interpretation of these is that they are the areas of these 10 triangles in suitable units. The asymptotic properties of this amplitude are related to the Einstein-Hilbert Lagrangian in [15],[16], and the classical solutions for a simplicial manifold are determined in [28]. We refer to the expression formed from the tetravalent diagram on a 4-simplex as a 10J-symbol, and the model constructed from them as the 10J model.

For the 15J model one takes the relativistic spin network



obtained by composing two trivalent vertices as the quantum state for the tetrahedron. This depends on the additional choice of a simple/balanced representation b for the centre edge.

The closed relativistic spin network for the 4-simplex is a trivalent graph called a 15J-symbol. The asymptotic properties of the 15J-symbol are related to the Einstein-Hilbert Lagrangian in [10]. The principal difference to the 10J model is that the amplitude for the 4-simplex depends on 15 irreducible representations, not 10. For each tetrahedron, one has a representation on each triangular face, together with a fifth representation associated to the tetrahedron. To evaluate the 15J-symbol one requires a choice of splitting the four faces into two pairs.

The geometrical picture of the 15J model in terms of bivectors is a little more complicated than the 10J case, as there are now five bivectors for a tetrahedron instead of four. Four of the bivectors are now

¹despite the fact that it is not one of the traditional 3NJ-symbols

associated to the faces of a combinatorial tetrahedron, but they no longer satisfy the geometrical constraints for the bivectors of a tetrahedron. The constraints that these satisfy are that the bivectors for one pair of faces and the fifth bivector lie in a hyperplane $H_1 \subset \mathbb{R}^4$, and the bivectors for the other pair of faces and the fifth bivector lie in a second hyperplane H_2 . This is clear by carrying out the analogous geometrical analysis to that in [15]; each vertex of a closed relativistic spin network is associated a unit vector $n \in \mathbb{R}^4$ and an edge is associated the bivector $*(n_1 \wedge n_2)$. The fact that there are two hyperplanes for the tetrahedron and not one is not accidental; the variable b is canonically conjugate to the angle between the two hyperplanes, so that if b is specified precisely then the angle is necessarily indeterminate, due to the uncertainty principle.

The trade-off between these two versions of the model is that introducing the extra representation on the tetrahedron increases the coupling between neighbouring 4-simplexes in a state sum model but destabilises the geometry of the 4-simplex. At present the best we can say is that the interpretation of the model is unclear at this point, but the clarity is neither better nor worse in its Lorentzian version.

1.2. Results in Lorentzian signature. The purpose of the present paper is to propose analogous models for the Lorentzian signature. As we will explain below, this essentially amounts to replacing U_q so(4) with the noncompact quantum group U_q sl(2, \mathbb{C}) \mathbb{R} , (known in the literature as the Quantum Lorentz Algebra) whose representations have been studied in [18, 19]. Some new phenomena occur due to the fact that the Lorentz group is not compact. For example, it seems no longer to be necessary to set the quantization parameter q equal to a root of unity, instead, we conjecture that any real number will do.

Unfortunately, the representation categories of noncompact Lie groups or quantum groups are more complex objects than the categories which have appeared in constructions of TQFTs or Euclidean general relativity. In order to formulate categorical state sums for these new categories, we will eventually (although not here), find it necessary to formulate the axioms for a new class of tensor categories to be called "measured categories". The new class of categories is a generalization of the theory of unitary representations of noncompact groups due to Mackey [21] and of the notion of fabrics due to Moussouris[22].

For the purposes of this paper, the difference is that the irreducible representations are not discrete, but form a measure space. This leads to a natural generalization of a state sum which we call a state integral.

It is not quite possible to give explicit formulae for our model with the present stage of knowledge of the representation theory of the Quantum Lorentz Algebra. The progress we have made is as follows

- 1. There is a natural definition of the 10J-symbol for SO(3,1) which we conjecture to be finite.
- 2. The integration measure for the state integral is a finite measure for the q-deformed case, the QLA.

In the case of 1. we present some arguments for this conjecture.

Obviously one would like to conjecture that the 10J–symbols remain finite for the QLA. However we do not yet have the correct definition of the q-deformation. Also, the question of whether there is a good definition of the 15J–symbol for SO(3,1) and for the QLA is not yet clear.

The following is an outline of the rest of this paper: chapter 2 gives a review of the representation theory of SO(3,1). Chapter 3 explains the geometry of relativistic bivectors and its relationship to representation theory and quantization. Chapter 4 deals with the question of the vertex for the theory. Chapter 5 discusses the state sum model for the theory in the divergent case of the classical Lorentz group, giving details of the definition of the Lorentzian relativistic spin network evaluation. Chapter 6 recalls the basic facts about the representation theory of the Quantum Lorentz Algebra and proposes a q-deformed model with integrals with respect to a finite measure. Finally, chapter 7 proposes some natural directions for the investigation of the model.

2. The representation theory of SO(3,1)

The purpose of this brief chapter is to acquaint the reader with the necessary facts about the representation theory of the Lorentz group and its Lie algebra, the Lorentz algebra [23, 24, 25].

The history of the subject is actually rather strange. It was originally studied by Dirac, who thought that representations of the Lorentz group, which he called "extensors" [26] might play a role in physics. In the subsequent development of quantum field theory, the representations of the Poincaré group which were important were not the ones which came from the Lorentz group, and physical interest in the subject disappeared (at least until the present). On the other hand, the work of Gelfand and Naimark [23, 24, 25] was extremely influential in mathematics.

In this paper we are only interested in the unitary irreducible representations of the Lorentz algebra called the principal series. We use unitary representations in order to have a probability interpretation. Existing state sum models use the Plancherel measure in the summation over representations. In the Plancherel measure for the Lorentz group the irreducibles which are not in the principal series have measure zero and can therefore be neglected.

The principal series representations are labelled by two parameters, one a half integer k, the other a continuous real parameter p; we can denote the representations R(k, p). The two parameters are naturally

combined into a single complex number, w = k + ip. There are no isomorphisms among them except that R(k,p) = R(-k,-p). Each is irreducible, infinite dimensional and isomorphic to its dual. Any unitary representation of the Lorentz algebra can be written as a direct integral of irreducibles. The regular representation can be written as a direct integral involving only the principal series.

Representations of the principal series are classified as fermions or bosons accordingly as k is half integral or integral. Both determine representations of the covering group of the Lorentz group, which is the group $\mathrm{SL}(2,\mathbb{C})$ considered as a real Lie group. The bosonic representations give representations of the Lorentz group itself. The tensor product of any two members of the principal series is a direct integral of all the bosonic members if both of the representations are bosons or both fermions, and a direct integral of all the fermions otherwise.

The Lorentz algebra can be thought of as $sl(2, \mathbb{C})$ considered as a real Lie algebra, or as $so(3, \mathbb{C})$ considered as a real Lie algebra. This corresponds to writing a general element of the Lorentz algebra as a sum of a rotation J and a boost K. Then J + iK is the corresponding element of $so(3, \mathbb{C})$. There are two invariant inner products on this Lie algebra,

$$\langle L, L \rangle = \frac{1}{2} L_{ab} L^{ab} = J^2 - K^2$$

and

$$\langle L, *L \rangle = \frac{1}{4} L_{ab} L^{cd} \epsilon^{abcd} = 2J \cdot K$$

The corresponding Casimir elements in the Lie algebra have eigenvalues

$$C_1 = k^2 - p^2 - 1$$
$$C_2 = 2kp$$

These are the real and imaginary parts of $w^2 - 1$.

3. Quantizing simple bivectors

The space of bivectors over \mathbb{R}^4 is a six dimensional real vector space. If we equip \mathbb{R}^4 with a Euclidean metric, then the bivectors have a natural identification with the Lie algebra so(4), which was necessary in the construction in [1]. As explained in [15, 7], the correct isomorphism is to take b = *L, or

$$b^{ab} = \frac{1}{2} \epsilon^{abcd} L^e{}_d g_{ec}$$

with g_{ec} the Euclidean metric. If take g to be a Lorentzian pseudometric on \mathbb{R}^4 (Minkowski space) instead of the Euclidean metric, then the bivectors are naturally identified with so(3,1) instead of so(4). Although changing the signature of the Lorentzian psuedometric would introduce a minus sign into the above identification, all bilinear conditions on the bivectors are unaffected.

The bivector associated to a triangle is the wedge of two edges, a *simple* bivector. The condition that the bivector is simple is

$$\langle b, *b \rangle = 0,$$

the same equation as for the Euclidean case.

In addition, we would like to differentiate spacelike, null and timelike simple bivectors, which correspond to planes in Minkowski space with an induced metric which is Euclidean, degenerate or Minkowskian. These are determined by the sign of $\langle b, b \rangle$. This is positive for spacelike bivectors, zero for null bivectors and negative for timelike bivectors. However the Hodge * interchanges timelike and spacelike bivectors, so the corresponding Lie algebra element L has $\langle L, L \rangle$ negative for spacelike bivectors, zero for null bivectors and positive for timelike bivectors.

The idea behind the construction of this paper, as well as the model in [1], is that having transformed all the variables for discretized GR into the form of constrained angular momenta (equals bivectors thought of as infinitesimal rotations) we quantize them the same way we quantize ordinary angular momenta, by replacing them with representations of the appropriate Lie algebra. Perhaps this is slightly obscured by the fact that in three dimensions bivectors are Hodge dual to vectors, so nonrelativistic angular momentum is written as a vector operator.

In this program, it is now desirable to find an expression of the constraint that a bivector be simple translated into the category of unitary representations of the Lorentz algebra.

The condition that the bivector is simple, $\langle b, *b \rangle = 0$, translates into the vanishing of the corresponding Casimir $C_2 = 2kp$. Thus either k = 0 or p = 0. The quantization of $\langle L, L \rangle$ is then $C_1 + 1 = k^2 - p^2$. If p = 0, then $\langle L, L \rangle$ is positive, and so the Lie algebra element L is spacelike. This means that the bivector b = *L is timelike. This leads us to propose the subcategory of representations R(k,0) as the quantization of the timelike bivectors, and the subcategory generated by the R(0,p) representations as a quantization of the spacelike ones.

Since the Hodge * interchanges timelike and spacelike bivectors, the space of simple timelike Lie algebra elements with a given square $\langle L, L \rangle$ is topologically the same as the corresponding space of spacelike elements. However the Poisson structures are different. Indeed, the spacelike simple Lie algebra elements include the subalgebra su(2), for which there is a quantization condition that the symplectic form is integral. This leads to a discrete series of representations. However the corresponding cohomology class for the timelike elements vanishes, so there is no quantization condition in this case and the parameter p is arbitrary.

There is another physical motivation for labelling the faces with the Hodge duals of their geometric bivectors. The approach we are exploring makes contact with the spin foam proposal of Rovelli and Reisenberger [34].

In that picture states for quantum gravity are described by embedded spin networks in 3d space. Their evolution is modelled by the world sheets of evolving spin networks which can change in time by developing vertices. On closer study, it seems that the kind of 2-complex they investigate is dual to a triangulation labelled as a term in our state sum. Although their approach has self-dual su(2) connections, the natural extension to so(4) connections would contain bivector operators which are canonically conjugate to the connection variables. As explained in [7], the Poisson structure which comes in here is the one determined by the Einstein action, and this identifies (dual) Lie algebra elements with bivectors using the Hodge *.

This contact with the kinematics of what is superficially a very different approach to quantizing gravity strengthens the specific proposal we have for the form of our state sum, which was suggested by the facts of the representation theory of the Lorentz group.

4. Vertices

In this section we consider the possible forms for the vertices for relativistic spin networks by considering the case q=1, in which the constructions can be described geometrically.

Naimark [24] has shown that between any triple of representations of $SL(2,\mathbb{C})$ satisfying the parity condition there is a unique (up to scalar multiple) intertwining operator. This means that, apart from normalisations, the trivalent vertex for the relativistic spin networks is defined.

To obtain a picture for the tetrahedron, we consider the possible 4-valent vertices. In the case of SO(4), the requirement that each tetrahedron lies in a hyperplane (3-plane) translated into the constraint that the sum of any pair of bivectors on two faces of a tetrahedron add up to form another simple bivector. This is still true in the Lorentzian case.

However it is not true that if the bivectors on the faces are spacelike then the sums of pairs will necessarily be spacelike as well. Likewise if the faces are timelike then the sum of any pair of bivectors need not be timelike. These facts are mirrored in the representation theory: tensor products of two even-spin R(k,0) representations will contain copies of the R(0,p) representations and vice versa. This will need to be taken into account below, when we decide exactly how to define a state sum model.

Our preferred representations R(k,0) and R(0,p) can be realised in the spaces of square integrable functions on the hyperboloids in Minkowski space, \mathbb{R}^4 with inner product $x \cdot x = (x^0)^2 - (x^1)^2 - (x^2)^2 - (x^3)^2$, using the Gelfand-Graev transform [30, 31]. We consider the cases Q_1 given by $x \cdot x = 1$, $x^0 > 0$, the positive null cone Q_0 given by $x \cdot x = 0$, $x^0 > 0$ and the de-Sitter space Q_{-1} , given by $x \cdot x = -1$. In [1], we noted that the simple/balanced representations of SO(4) could be realised in the space of functions on S^3 . The relativistic spin network formalism in terms of functions on S^3 was developed in [15, 29]. This can be directly generalised to the present case in a number of ways by replacing S^3 with either one of the hyperboloids Q_1 , Q_0 or Q_{-1} .

The representations of SO(3,1) have a Fourier decomposition as the following direct integrals and direct sums:

$$L^{2}(Q_{1}) \cong \bigoplus_{p} R(0, p) d\mu_{p}$$

$$L^{2}(Q_{0}) \cong 2 \bigoplus_{p} R(0, p) d\mu_{p}$$

$$L^{2}(Q_{-1}) \cong \left(2 \bigoplus_{p} R(0, p) d\mu_{p}\right) \bigoplus \left(\bigoplus_{k} R(k, 0)\right).$$

The notation $\oplus d\mu_p$ indicates a direct integral, using the measure $d\mu_p = p^2 dp$, which is the Plancherel measure restricted to k = 0. An element of the direct integral is a vector function of $p, v_p \in R(0, p)$, with square $\int ||v_p||^2 d\mu_p$. The 2 indicates that the following term appears as a summand twice.

This decomposition can be understood in the following way. The Casimir operator C_1 is the Laplacian on Q_1 . So the irreducible representation R(0, p) can be considered the space of solutions to the eigenvalue equation for the Laplacian with eigenvalue $-1 - p^2$.

The Casimir C_1 is also the wave operator on Q_{-1} with eigenvalues either $-1 - p^2$ or k^2 . In this case one has solutions of the wave equation associated to both the time orientations, somewhat analogous to positive energy and negative energy solutions of the wave equation in Minkowski space. This gives the two copies of R(0, p) in the Fourier decomposition of $L^2(Q_{-1})[35]$. In addition there are the 'tachyons', giving the R(k,0). For the hyperboloid Q_0 , one has a degenerate version of these formulae.

One would like to have an intuitive understanding of these Fourier decompositions in terms of the quantization of bivectors. Bivectors in Minkowski space determine geodesics on the hyperboloids. For example, a spacelike simple bivector is Hodge dual to an oriented timelike plane through the origin in Minkowski space, which intersects Q_1 in an oriented geodesic. Following Mukunda [17], quantum mechanics on Q_1 has as a classical limit the motion of free particles on Q_1 . These move along geodesics given by the Hamiltonian $H = P^2$ on the phase space T^*Q , where P is the coordinate for the cotangent space. In fact,

the constraint surface $\{H = \text{constant}\}\$ decomposes into the orbit space under this flow, namely the space of geodesics on Q_1 , or the space of simple spacelike bivectors in Minkowski space.

Each timelike plane intersects Q_0 and Q_{-1} in *two* timelike or null geodesics each, one future-directed and one past-directed. This explains the multiplicity 2 of the R(0,p) in the Fourier decompositions of these spaces.

Likewise, a timelike simple bivector is Hodge dual to a spacelike plane through the origin in Minkowski space, which intersects Q_{-1} in exactly one spacelike geodesic. These planes do not intersect Q_0 or Q_1 . Thus the R(k,0) representations occur only in the Fourier decomposition of Q_{-1} . In this way, we understand the multiplicities in the above Fourier decompositions.

The Gelfand-Graev transform gives precise formulae for the decompositions. The case of the three-dimensional hyperbolic space Q_1 is particularly important in the following, so we develop the formulae here. The other cases have analogous formulae.

In general the representations R(k,p) can be realised in the space of square-integrable sections of a line bundle over $\mathbb{C}P^1$. However for the R(0,p) one can simplify this to give the representation in the space of homogeneous functions of degree -1+ip on the light cone in Minkowski space.² This means an element f of this space satisfies $f(\lambda \xi) = \lambda^{-1+ip} f(\xi)$ for null vectors ξ and for any real number $\lambda \neq 0$. The inner product on this space is determined by the integral

(1)
$$\int_{\Gamma} \bar{f}_1(\xi) f_2(\xi) d\xi$$

over the two-sphere Γ given by the null vectors satisfying $\xi^0 = 1$. The measure is the standard rotationally-invariant measure $\mathrm{d}\xi$, normalised to total volume 1. The Gelfand-Graev transform gives the function

$$\hat{f}(x) = \int_{\Gamma} f(\xi)(x \cdot \xi)^{-1-ip} d\xi$$

defined on Q_1 .

Our proposal for a k-valent relativistic spin network vertex for SO(3,1) is given by a map $R(0, p_1) \otimes ... \otimes R(0, p_k) \to \mathbb{C}$ by the formula

$$f_1 \otimes f_2 \otimes \dots f_k \mapsto \frac{1}{2\pi^2} \int_Q \hat{f}_1(x) \hat{f}_2(x) \dots \hat{f}_k(x) dx.$$

In this formula, Q is one of the hyperboloids $Q_{\pm 1}$, Q_0 , and \hat{f} denotes one of the representations of f as a function on the hyperboloid, as given for example for the case of Q_1 by the preceding formula. The measure $\mathrm{d}x$ is the standard Riemannian (or pseudo-Riemannian) volume measure on Q. The map is not defined on every element of the tensor product,

²Gelfand and coauthors use the parameter $\rho = 2p$.

and the important point is to understand it as a generalised function of the p_i variables as well as the ξ_i .

Alternatively the vertex can be defined by the formula for the kernel of the integral. For the case of Q_1 this is

$$V(\xi_1, \xi_2, \dots, \xi_k) = \frac{1}{2\pi^2} \int_{Q_1} (x \cdot \xi_1)^{-1 - ip_1} (x \cdot \xi_2)^{-1 - ip_2} \dots (x \cdot \xi_k)^{-1 - ip_k} dx$$

Each of the representations for the different hyperboloids gives rise to a particular formula for the vertex (of arbitrary valence) for the relativistic spin networks. Using Q_1 , there is a single vertex for relativistic spin networks labelled with R(0,p). The uniqueness is due to the fact that each irreducible appears only once in the decomposition of $L^2(Q_1)$. Remarkably, this also implies a decomposition of the four-valent vertex

(2)
$$c = \int_{p} d\mu_{p}$$

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with the intermediate edge labelled with the R(0,p). This formula is obtained by applying the Fourier decomposition to the intermediate product function $\hat{f}_1(x)\hat{f}_2(x)$. As this is also a function on Q_1 , its decomposition only involves the R(0,p). Precise formulae and a proof of this decomposition are given below in section 5.1. This formula is a direct analogue of the corresponding formula for the Euclidean case which formed the original definition of the four-valent relativistic spin network vertex in [1]. The analogy is given in section 5.4.

Our interpretation of this formula is of a tetrahedron which lies in a spacelike hypersurface. In this situation, the sum of the two bivectors for two faces is always again a simple spacelike bivector. This is reflected in the fact that the decomposition formula only requires intermediate representations of the form R(0, p).

Using Q_{-1} , there are a number of vertex formulae given by analogous integrals. If the representation on a free end is R(0,p), then one has to specify whether the representation is to be realised in $L^2(Q_{-1})$ as the future- or past-directed solutions of the wave equation. These two transforms are given by

$$\hat{f}(x) = \int_{\Gamma} f(\xi) G^{\pm}(x, \xi) d\xi$$

with

$$G^{+}(x,\xi) = \begin{cases} (x \cdot \xi)^{-1-ip} & x \cdot \xi > 0\\ 0 & x \cdot \xi < 0 \end{cases}$$

and $G^-(x,\xi) = G^+(-x,\xi)^3$ Also, it is possible to put the R(k,0) on the free ends, in only one way, using the formulae in [31].

Our interpretation of these 4-valent vertices is that they represent tetrahedra which lie in a timelike (Minkowski signature) hypersurface in Minkowski space. Accordingly the faces of such a tetrahedron can be timelike, either future-pointing or past pointing, or spacelike. These possibilities correspond to the different possible vertex formulae. There is also a decomposition formula analogous to (2) for this case, which entails the use of two copies of R(0,p) (the choice of G^+ or G^-) and the use of the R(k,0) representations. This corresponds to the fact that in a Minkowski signature tetrahedron the sum of the bivectors for a pair of faces can be spacelike (future or past oriented) or timelike.

Finally, the analogous formulae for Q_0 give null tetrahedra.

5. The state sum model

We shall now choose a geometric form for the model. Let us assume that the classical geometry is a triangulation of our manifold into 4-simplices all of whose boundary tetrahedra are spacelike. This means that all of the bivectors on the 2-simplices and all of the sums of bivectors of 2-simplices in the boundary of a common tetrahedron must be simple and spacelike. As discussed in the previous section, this is consistent with a categorical calculus in which the representations R(0, p) only are used everywhere. This is the simplest form for a model, though we note that it may be interesting to investigate the other possibilities.

For the 10J version of the model, a simplicial manifold is labelled with a value of p on each triangle, and the weight for this state is the product of the symbols for each 4-simplex. In the 15J version of our model there is additionally a value of p on each tetrahedron, and we use the product of the 15J-symbols. The model is formally the integral with the measure $d\mu_p$ on each variable in the simplicial manifold.

Of course, a model constructed from representations of $sl(2, \mathbb{C})$ would involve either an integral over all values of p (or for other forms of the model a sum over all values of k). This would make it divergent. In [1] we solved the analogous problem by passing to a quantum group. We shall see in section 6 how this seems to work out in the Lorentzian case. In this section we state the form of the model for q = 1.

5.1. **Relativistic spin network evaluation.** Firstly there is the question of how to evaluate the categorical diagrams we are to associate with the 4-simplices.

³This differs from the integral transform given in [31], which is valid for functions which are even under inversion.

Given a function $h \in L^2(Q_1)$ the p-th irreducible component is given by

 $f_p(\xi) = \frac{1}{2\pi^2} \int_{Q_1} h(x) (x \cdot \xi)^{-1+ip} dx$

giving a homogeneous function on the light cone, $\xi \cdot \xi = 0$. The inverse transform is

$$h(x) = \int_0^\infty d\mu_p \int_{\Gamma} f_p(\xi) (x \cdot \xi)^{-1-ip} d\xi.$$

Composing these two transforms gives the delta function $\delta(x, y)$ on Q_1 . However if one does the same calculation but does not integrate over p, the result is a projection operator onto the p-th irreducible component h_p of the function h on Q_1 . The kernel of this operator can be explicitly evaluated. The projection is given by

$$h_p(x) = \frac{1}{2\pi^2} \int_{Q_1} K_p(x, y) h(y) dy$$

where

(3)
$$K_p(x,y) = \int_{\Gamma} (x \cdot \xi)^{-1-ip} (y \cdot \xi)^{-1+ip} d\xi = \frac{\sin pr}{p \sinh r},$$

r being the hyperbolic distance (boost parameter) between x and y. For a fixed x, the function of y is called the zonal spherical function [35]. It is the solution of the Helmholtz equation which is spherically symmetric about x.

One can check explicitly that the delta function is regained by integrating over p

(4)
$$\int_0^\infty K_p(x,y) d\mu_p = 2\pi^2 \delta(x,y)$$

For a fixed x, $K_p(x,y)$ gives a continuous function of y which is absolutely bounded by the value 1 at x and decays exponentially at infinity, but is not square integrable. The normalisation is in fact

$$\frac{1}{2\pi^2} \int_{Q_1} K_p(x, y) K_{p'}(y, z) dy = K_p(x, z) \frac{\delta(p - p')}{p^2},$$

expressing that fact that K is a projection to the p-th Fourier component on Q_1 . Here it is assumed that p, p' > 0.

Now we can give the rules for evaluating a relativistic spin network. The network is a graph with each edge labelled by a parameter p. The graph is allowed to have a boundary. This means that the edges do not have to end in vertices of the graph. The ends of the edges which do not meet vertices are called free ends, and the set of all these is the boundary of the graph. If there are no free ends the graph is called a closed graph.

The naive evaluation associates one variable ξ to each edge and is given by taking the product of one kernel $V(\xi_1, \ldots, \xi_k)$ for each vertex

and integrating along the interior edges (those without free ends) using the inner product (1) in the ξ variables.⁴

For the interior edges this procedure gives a factor of $K_p(x_1, x_2)$ for each edge. This is because performing the transform from functions on Q_1 to R(0, p) and back to the space of functions on Q_1 at the next vertex is the same as inserting $K_p(x, y)$ for the edge.

This can be illustrated by giving the promised proof of (2). This uses first equation (4), then (3).

$$= \int_{Q_1} \frac{\mathrm{d}x}{2\pi^2} \int_{Q_1} \frac{\mathrm{d}y}{2\pi^2} \int_0^\infty \mathrm{d}\mu_p \ K_p(x,y) (x \cdot \xi_1)^{-1-ip_1} (x \cdot \xi_2)^{-1-ip_2} (y \cdot \xi_3)^{-1-ip_3} (y \cdot \xi_4)^{-1-ip_4}$$

$$= \int_0^\infty \mathrm{d}\mu_p \int_{\Gamma} \mathrm{d}\xi \ V(\xi_1, \xi_2, \xi) V(\xi, \xi_3, \xi_4)$$

$$= \int_0^\infty \mathrm{d}\mu_p \int_{P_2} \frac{\mathrm{d}y}{p_4} \int_{P_4} \frac{\mathrm{d}y}{p_4} \int_{P_4}$$

5.2. The regularised evaluation for closed networks. For closed networks the naive evaluation formula can be re-expressed entirely in terms of the kernels K. In this section we give the definition of the evaluation for closed networks using these kernels as we shall use it in the rest of this paper. It will be necessary to modify the naive evaluation formula a little to obtain the actual definition of the evaluation which we are to use.

Each vertex is associated a variable $x \in Q_1$. Each edge is associated the factor $K_p(x_1, x_2)$, the variables being the ones associated to the vertices at either end of the edge. The naive evaluation is then

(5)
$$\int_{Q_1^n} \prod K_{p(ij)}(x_i, x_j) \mathrm{d}x_1 \mathrm{d}x_2 \dots \mathrm{d}x_n.$$

The evaluation of closed networks is a problem. Since the irreducible representations are infinite dimensional, we cannot trace on them. This is because the trace of the identity operator is infinite.

In our integral definition this is reflected in the fact that the integral is invariant under SO(3,1) and the orbits are not compact, so one has infinite factors for the volume of each orbit.

⁴The hermitian inner product (1) is written as a bilinear product by replacing p with -p in one of the two factors.

There are two essentially equivalent ways of dealing with this. The definition we adopt is simply to remove the integration over the variable in Q_1 at one of the vertices in (5). Using the Lorentz invariance, it does not matter which variable is chosen for this. We take the variable x_1 to be fixed.

Definition 1. The regularised evaluation for closed networks is

(6)
$$\int_{O_1^{n-1}} \prod K_{p(ij)}(x_i, x_j) \mathrm{d}x_2 \dots \mathrm{d}x_n.$$

Due to the Lorentz invariance, this integral is independent of the chosen value for x_1 . This definition is similar to the suggestion in [8] that we can open up any closed network by cutting one edge to give a network with two free ends and regard the network as an intertwiner from one irreducible to another. This gives a multiple of the identity operator. This multiple is then the evaluation of the original closed network.

The evaluation is illustrated by several very simple cases. Firstly, a graph given by a single loop with one vertex on it



has the evaluation

$$K_p(x,x) = 1.$$

A graph with two vertices on a loop



has the evaluation

$$\frac{1}{2\pi^2} \int_{O_1} K_a(x, y) K_b(y, x) dy = \frac{\delta(a - b)}{a^2}.$$

This elementary example illustrates very clearly that the relativistic spin network evaluation may be distributional in the spin parameters a, b. This means that for particular values of these parameters (here a = b) the evaluation may not have a finite value.

Also we note that in the simpler case of a closed network with two vertices joined with just one edge,



the evaluation is a divergent integral for all values of the spin parameter.

$$\frac{1}{2\pi^2} \int_{Q_1} K_a(x, y) \mathrm{d}y = \infty.$$

The theta symbol with two vertices and three edges



has the evaluation

$$\frac{1}{2\pi^2} \int_{Q_1} K_a(x, y) K_b(x, y) K_c(x, y) dy$$

$$= \frac{2}{\pi abc} \int_0^\infty \frac{\sin ar \sin br \sin cr}{\sinh r} dr$$

$$= \frac{1}{4abc} \left(f(b+c-a) + f(c+a-b) + f(a+b-c) - f(a+b+c) \right)$$

where

$$f(k) = \frac{2}{\pi} \int_0^\infty \frac{\sin kr}{\sinh r} dr = \tanh(\frac{\pi}{2}k).$$

For large values of |k|, f(k) tends to ± 1 . As a consequence, when the Euclidean triangle inequalities for a,b,c are satisfied the value of the theta symbol approximates 1/(2abc). When the inequalities are violated exactly one of the four f terms becomes negative, giving approximately zero for the evaluation of the theta symbol in this limit. In fact the value dies away exponentially fast as a,b,c increase away from the critical values of a degenerate triangle, characteristic of quantum effects in a classically forbidden region of configurations.

In terms of bivectors this agrees with the interpretation developed above. The simple spacelike bivectors correspond to planes in Minkowski space which lie in a common spacelike hypersurface in Minkowski space. Whenever these three bivectors add to zero then their magnitudes satisfy the Euclidean triangle inequalities.

A similar analysis can be carried out for the graph with two vertices and four connecting edges.



This graph is important because it gives a magnitude for the vertex for the tetrahedron. For this graph the evaluation is

$$\frac{1}{4abcd} \Big(g(b+c+d-a) + g(c+d+a-b) + g(d+a+b-c) + g(a+b+c-d) \\ - g(b+c-a-d) - g(c+a-b-d) - g(a+b-c-d) - g(a+b+c+d) \Big)$$

where

$$g(k) = \frac{k}{2} \coth(\frac{\pi}{2}k).$$

For large k, the function g is asymptotically |k|/2. If one of four spins is bigger than the sum of the other three, say d > a + b + c, then the amplitude is asymptotically zero, just as for the theta symbol. However this condition occurs precisely when it is impossible to form a spacelike tetrahedron in Minkowski space with these numbers as the areas of the faces. This confirms our interpretation of the four-valent vertex as the quantization of a spacelike tetrahedron.

For more complicated graphs it is a non-trivial task to determine whether our expression for the evaluation is finite. In the special case of a 10J-symbol, we give arguments that the integral is finite and determines a function of the p. We do not at this point know a finite expression for a 15J-symbol, or even a 6J-symbol. If this is not just an artifact of our knowledge, it may be that only the 10J model survives in Lorentzian signature. The evaluation of relativistic spin networks is full of interesting open questions.

5.3. Finite 10J-symbols For $SL(2,\mathbb{C})$. The 10J-symbol is the evaluation of the relativistic spin network based on the complete graph on 5 vertices, all of whose edges are labelled with R(0,p) representations of $SL(2,\mathbb{C})$.

Conjecture 1. The regularised evaluation of the 10J-symbol labelled with R(0, p) representations is finite.

Evidence for the conjecture: This integral is similar in form to a Feynman integral on hyperbolic space. The kernel K(x, y) is bounded as $x \to y$, so only infrared divergences need be considered. In other words, the only divergence possible would be at infinity in hyperbolic space. We therefore need to use two facts: the radial growth of the area of a large sphere in Q_1 , and the asymptotic behavior at infinity of the kernel K.

Using the fact that the area of the sphere is asymptotically e^{2r} , while the K is asymptotically e^{-r} it is possible to make an estimate for the integral expression (6). A delicate analysis shows that the expression is in fact absolutely convergent, even if the sine terms in K are omitted and K is approximated by e^{-r} for large r.

Thus the behaviour of the integral (6) as all variables go to infinity separately is dominated by the integral of a positive function, and apart from the trivial factors of 1/p, is independent of the values of the spin labels p defining the representations on the edges.

In order to show that the integral is actually finite we need to consider also the regions where some vertices go to infinity and some do not. This corresponds to subdivergences in the standard Feynmanological language. We believe they do not appear in our case, but further analysis is needed. It is interesting to note that the analogous analysis for a 6J–symbol gives an indeterminate expression and it is not clear if the corresponding integral converges. It would be interesting to look for a regularisation procedure to give finite values for all diagrams in this category.

5.4. Comparision with the Euclidean case. In our original paper on relativistic spin networks, we used the representation theory of SO(4) rather than SO(3,1). We call this the Euclidean case. In this, we used irreducible unitary representations, which are finite dimensional. For these representations the spin network evaluations always exist as there is no difficulty taking the trace of a finite dimensional matrix. At first sight, the formalism for the infinite dimensional representations of the Lorentz group looks completely different. However the formulae we obtain have a strong similarity, and can say that the two evaluations are analogous but not the same. The irreducible representations that are used in the Euclidean case, the simple/balanced ones, are labelled by the spin n, an integer⁵. The following considerations show that the Lorentzian relativistic spin network evaluation can be considered as an extension of the Euclidean evaluation to the case where n is a complex number of the form -1 + ip, for $p \in \mathbb{R}$.

In [15] the relativistic spin network evaluation for SO(4) was written in terms of integrals over S^3 . This space is analogous to the hyperboloid Q_1 in the present work. Each edge is labelled with an integer n, and the kernel for each edge in [15] is

$$K_E = \frac{\sin(n+1)\theta}{\sin\theta},$$

where θ is the distance between two points on S^3 . On substituting $r = i\theta$ and p = -i(n+1), the kernel K for the Lorentz group becomes exactly 1/(n+1) times the formula for the Euclidean kernel K_E . This suggests that a better comparison between the magnitudes of Lorentzian and the Euclidean evaluations is to divide the later by a factor of n+1 for each edge. Indeed this is confirmed by the example of the loop with one vertex. In [15] the evaluation of the loop is $(-1)^n(n+1)$, whereas here it is 1. With the adjustment, the evaluations agree up to a phase factor. In general understanding the comparison of the phase factors would require a deeper investigation.

For the theta symbol, the Euclidean evaluation gives 1 if the three integer spin labels satisfy the triangle inequalities for a Euclidean triangle and sum to an even integer, and zero otherwise. For the Lorentzian evaluation, as computed above, the spin labels a, b, c are continuous parameters and, after making the adjustment of multiplying by abc (equivalent in magnitude to dividing the Euclidean formula by factors of n + 1), the evaluation interpolates smoothly between asymptotic

⁵This parameter is often given as a half-integer j = n/2.

values of 1/2 far into the interior of the region where the triangle inequalities are satisfied and 0 far into the region where they are violated.

The integration measure is analogous too, as the factor of $1/(2\pi^2)$ which has been included with each integration on the unit hyperboloid is the volume of the unit three-sphere; so the analogous measure on S^3 is normalised to total volume 1. This is the measure used in [15].

The decomposition formula (2) is directly analogous once one makes the correction of a factor of n+1 for the middle edge in the Euclidean evaluation. After this correction, the Euclidean formula would be to sum over the spins on the middle edge with weight $(n+1)^2$ (again ignoring phase factors). This is directly analogous to the measure $d\mu_p = p^2 dp$ on substituting n + 1 = ip.

6. Passing to the Quantum Lorentz Algebra: a finite MODEL?

The process of passing to the representation category of a quantum group should not be thought of merely as a clever regularization scheme for this family of models. Quantum groups fit very firmly into the program of noncommutative geometry. A quantum group is a noncommutative space with a symmetry structure like a Lie group. In fact, the noncompact quantum group which is referred to in the literature as the Quantum Lorentz Algebra (QLA) has a good C^* algebra version [19, 20]. The set of irreducible representations of a C^* algebra is the noncommutative analog of the set of points of a space. Thus, the construction of the model in this paper can be viewed as an exploration of a noncommutative version of general relativity. The approach of this paper allows us to interpret the discoveries about the representations of the QLA as a species of quantum geometry. In terms of classical physics, the q deformation can also be interpreted as the introduction of a cosmological constant [32, 33].

The representation theory of the QLA [19] is not as well understood as that of the classical Lorentz algebra. There are two possible forms of the QLA, one with the deformation parameter real and one where it is a complex phase. It seems that only the real case has been studied in the literature, so we shall attempt to use it in our construction. As in the classical case, the irreducible unitary representations are infinite dimensional and classified by two parameters, one discrete and one continuous. The first difference is that the continuous parameter is only allowed to take values in a bounded set of finite measure, which depends on the discrete parameter.

The Plancherel measure (rather subtly defined) is given in [19] as

$$\frac{h}{2\pi}(\cosh(2hk) - \cos(2hp))\mathrm{d}p,$$

where $q = e^h$. This measure is defined over $p \in [-\pi/h, \pi/h]$ and $k \in \mathbb{Z}$. However, since the values (k, p) and (-k, -p) are equivalent, the measure is integrated over one half of this region, a fundamental domain for this identification.

For k = 0, the measure reduces to

$$\frac{h}{2\pi} \left(1 - \cos(2hp) \right) \mathrm{d}p$$

over the interval $[0, \pi/h]$, which is a finite measure.

Now we can see that the effect of passing to the QLA is to make the Plancherel measure restricted to the quantum version of the spacelike simple bivectors a finite measure.

On the other hand, the sum corresponding to the timelike simple bivectors is not truncated. This is consistent with our choice of model integrating over the representations of the form R(0,p), thinking of them as the Hodge duals of spacelike bivectors. (At present we are actually constrained to do this because the version of the QLA with a complex phase for q is not studied. One could easily conjecture that passing to a root of unity would give a truncation in k. This is a subject for further study).

The rest of the situation with respect to the representations of the QLA has not yet been fully clarified. The 3J–symbols (trivalent vertices) have been defined only for a finite dimensional representation paired to a unitary one. On the other hand, the universal R matrix is known, and Buffenoir and Roche have announced a program to find the missing 3J–symbols [19].

7. Prospects

Clearly, the first item on the agenda in pursuing this model will be a careful study of the 3J, 6J 10J and 15J—symbols of the QLA. Once the definitions of these symbols are clear, a number of natural questions will arise.

In the first place it will be interesting to see if asymptotic formulae for the relevant q-deformed symbols can be found as in the compact case. This will allow us to see if the argument recovering the Einstein Hilbert Lagrangian in the classical limit for the Euclidean signature case can be extended to Lorentzian signature, as it does in 2+1 dimensions [8].

Secondly, it will be necessary to study the state integral carefully to find out if the integrand contains any singularities which are not integrable.

Beyond this, there are many interesting questions we would like to study about the model. One would like to see whether small disturbances in initial conditions propagate causally. The model differs from other quantum gravity models in that it allows a continuous spectrum for the area of a spacelike surface. It might be interesting to see if this can generate any interesting predictions for black hole spectra.

Farther down the line, we would like very much to know what the model does as we refine the triangulation on which it is based. Good behavior might tell us how to use the model to construct an actual theory of quantum general relativity.

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